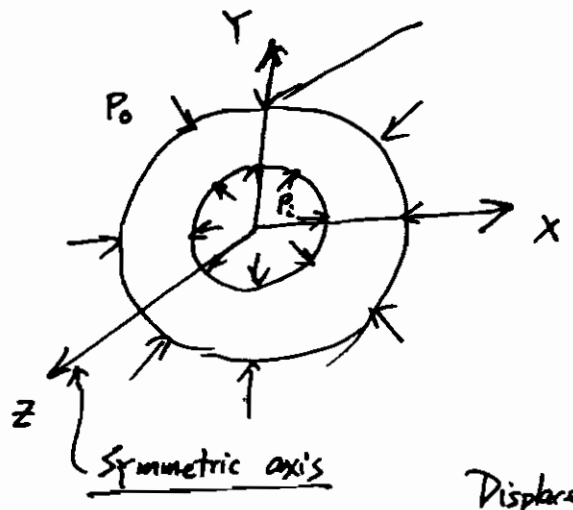


# Lecture 14 Axisymmetric Loaded Member: The Thick Cylinder

Axis-symmetric problem: both deformation and external load distribution are symmetric with respect to z-axis



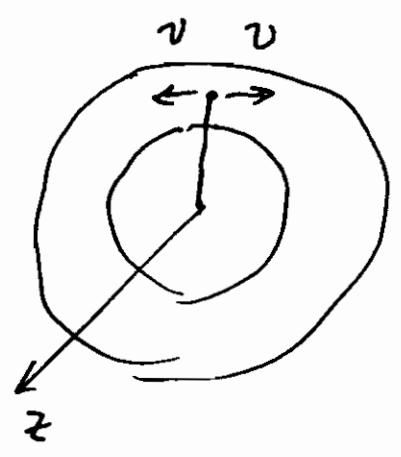
Applications: pipes, pressure vessels  
dome, tunnel structures

Consequences  
displacement fields, stress/strain fields are independent from  $\theta$

### Displacements

$$\begin{cases} u_r = u(r) \leftarrow \text{radial displacement} \\ u_\theta = v(r) \leftarrow \text{tangential displacement} \end{cases}$$

Let's examine  $u_\theta = v(r)$

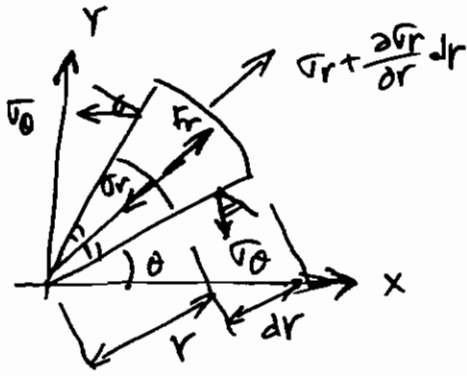


which  $v$ ?  $v = -v \Rightarrow \boxed{v \equiv 0}$

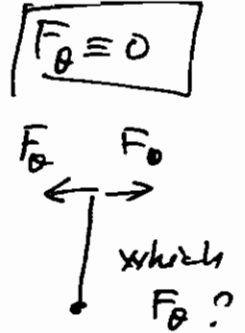
Remark In 3D, the axis-symmetric problem is described as follows

$$\begin{aligned} u_r &= u(r, z) \\ u_\theta &= v \equiv 0 \quad \leftarrow \text{In literature} \\ u_z &= w(r, z) \end{aligned}$$

§14-1 Equilibrium equation



$$\begin{cases} \sigma_r = \sigma_r(r) \\ \sigma_\theta = \sigma_\theta(r) \\ \tau_{r\theta} = 0 \end{cases}$$



$\Sigma F_r = 0$

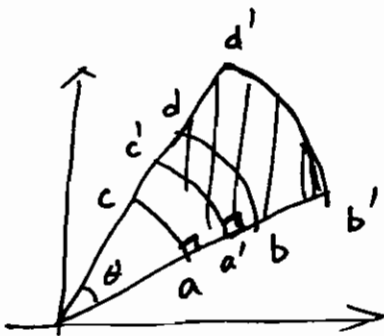
$$(\sigma_r + \frac{\partial \sigma_r}{\partial r} dr)(r+dr)d\theta - \sigma_r r d\theta - 2\sigma_\theta \sin \frac{d\theta}{2} \cdot dr + F_r (rd\theta)dr = 0$$

$$\sigma_r dr d\theta + \frac{\partial \sigma_r}{\partial r} dr (r+dr)d\theta - \sigma_\theta d\theta dr + F_r r d\theta dr = 0$$

$$\Rightarrow \boxed{\frac{\partial \sigma_r}{\partial r} + \frac{\sigma_r - \sigma_\theta}{r} + F_r = 0}$$

Geometric equations (strain)

No shear strain since the right angle remains 90°



$a: 2r(r)$	$a': r + u(r)$
$b: u(r+dr)$	$b': r+dr + u(r+dr)$

$$\epsilon_r = \frac{\overline{a'b'} - \overline{ab}}{\overline{ab}} = \frac{[dr + \overbrace{u(r+dr) - u(r)}^{\Delta u \leftarrow \text{elongation}}] - dr}{dr} = \frac{du}{dr}$$

$$\epsilon_\theta = \frac{\widehat{a'c'} - \widehat{ac}}{\widehat{ac}} = \frac{(r+u(r))d\theta - rd\theta}{rd\theta} = \frac{u}{r}$$

$$\epsilon_{r\theta} = 0$$

Assume that both ends of the cylinder are free, i.e.  $\sigma_z = 0$ .

By generalized Hooke's law (plane stress)

$$\epsilon_r = \frac{du}{dr} = \frac{1}{E} (\sigma_r - \nu \sigma_\theta)$$

$$\epsilon_\theta = \frac{u}{r} = \frac{1}{E} (\sigma_\theta - \nu \sigma_r)$$

$$\boxed{\sigma_{r\theta} = \frac{1}{E} \tau_{r\theta} \equiv 0}$$

$$\sigma_r = \frac{E}{1-\nu^2} \left( \frac{du}{dr} + \nu \frac{u}{r} \right)$$

← plane stress  
 $\nu_z = 0$

$$\sigma_\theta = \frac{E}{1-\nu^2} \left( \frac{u}{r} + \nu \frac{du}{dr} \right)$$

$$\tau_{r\theta} = 0$$

Recall the equilibrium equations in polar coordinates

$$\begin{cases} \frac{\partial \sigma_r}{\partial r} + \frac{1}{r} \frac{\partial \tau_{r\theta}}{\partial \theta} + \frac{\sigma_r - \sigma_\theta}{r} + F_r = 0 \\ \frac{1}{r} \frac{\partial \tau_{r\theta}}{\partial \theta} + \frac{\partial \tau_{r\theta}}{\partial r} + \frac{2\tau_{r\theta}}{r} + F_\theta = 0 \end{cases}$$

⇒

$$\boxed{\frac{d\sigma_r}{dr} + \frac{\sigma_r - \sigma_\theta}{r} + F_r = 0}$$
  
$$F_\theta = 0$$

In absent of body force, we have

$$\boxed{\frac{d\sigma_r}{dr} + \frac{\sigma_r - \sigma_\theta}{r} = 0}$$

⇒

$$\frac{E}{1-\nu^2} \left( \frac{d^2u}{dr^2} + \frac{\nu}{r} \frac{du}{dr} - \frac{\nu}{r^2} u \right)$$

$$+ \frac{1}{r} \frac{E}{1-\nu^2} \left( (\nu) \frac{du}{dr} + (\nu-1) \frac{u}{r} \right) = 0$$

$$\boxed{\frac{d^2u}{dr^2} + \frac{1}{r} \frac{du}{dr} - \frac{u}{r^2} = 0}$$

← Governing equation

⇒

$$\boxed{\frac{d}{dr} \left\{ \frac{1}{r} \frac{d}{dr} (ru) \right\} = 0}$$

← layer form

$$\frac{d}{dr} \left[ \frac{1}{r} \left( r \frac{du}{dr} + u \right) \right] = \frac{d}{dr} \left[ \frac{du}{dr} + \frac{u}{r} \right] = \frac{d^2u}{dr^2} + \frac{1}{r} \frac{du}{dr} - \frac{u}{r^2} = 0$$

step 1:  $\frac{1}{r} \frac{d}{dr} (ru) = c_1'$

$$\frac{d}{dr} (ru) = c_1' r$$

step 2:  $ru = \frac{c_1' r^2}{2} + c_2'$

$$u = \frac{c_1' r}{2} + \frac{c_2'}{r} = c_1 r + \frac{c_2}{r}$$

Then

$$\epsilon_r = \frac{du}{dr} = c_1 - \frac{c_2}{r^2}$$

$$\epsilon_\theta = \frac{u}{r} = c_1 + \frac{c_2}{r^2}$$

$$\sigma_r = \frac{E}{1-\nu^2} \left( \frac{du}{dr} + \nu \frac{u}{r} \right) = \frac{E}{1-\nu^2} \left( c_1 (1+\nu) - c_2 \frac{(1-\nu)}{r^2} \right)$$

$$\sigma_\theta = \frac{E}{1-\nu^2} \left( \frac{u}{r} + \nu \frac{du}{dr} \right) = \frac{E}{1-\nu^2} \left( c_1 (1+\nu) + c_2 \frac{(1-\nu)}{r^2} \right)$$

$$\sigma_r + \sigma_\theta = \frac{2E c_1}{1-\nu^2} (1+\nu) = \frac{2E c_1}{1-\nu} = \text{const.}$$

$$\left\{ \begin{array}{l} \epsilon_z = -\frac{\nu}{E} (\sigma_r + \sigma_\theta) = -\frac{2\nu c_1}{1-\nu} = \text{const.} \quad \leftarrow \boxed{\text{plane stress}} \\ \epsilon_z = -\nu (\sigma_r + \sigma_\theta) = \text{const.} \quad \leftarrow \text{plane strain} \end{array} \right.$$

Consider stress boundary conditions: To determine  $c_1$  &  $c_2$ .

$$\sigma_r|_{r=a} = -P_i \quad \leftarrow \text{inner radius}$$

$$\sigma_r|_{r=b} = -P_o \quad \leftarrow \text{outer radius}$$

$$\frac{E}{1-\nu^2} \begin{bmatrix} (1+\nu), & -\frac{(1-\nu)}{a^2} \\ (1+\nu), & -\frac{(1-\nu)}{b^2} \end{bmatrix} \begin{bmatrix} C_1 \\ C_2 \end{bmatrix} = \begin{bmatrix} -P_i \\ -P_o \end{bmatrix}$$

Solve for  $C_1$  &  $C_2$

$$C_1 = \left(\frac{1+\nu}{E}\right) \frac{a^2 P_i - b^2 P_o}{b^2 - a^2}$$

$$C_2 = \left(\frac{1+\nu}{E}\right) \frac{a^2 b^2 (P_i - P_o)}{b^2 - a^2}$$

Remarks

has nothing to do with  $\nu$  &  $E$   
So they are valid for both

Finally,

$$\begin{aligned} \sigma_r &= \frac{a^2 P_i - b^2 P_o}{b^2 - a^2} - \frac{(P_i - P_o) a^2 b^2}{(b^2 - a^2) r^2} \\ \sigma_\theta &= \frac{a^2 P_i - b^2 P_o}{b^2 - a^2} + \frac{(P_i - P_o) a^2 b^2}{(b^2 - a^2) r^2} \end{aligned}$$

$$a \leq r \leq b$$

$$u = \left(\frac{1+\nu}{E}\right) \frac{(a^2 P_i - b^2 P_o) r}{b^2 - a^2} + \left(\frac{1+\nu}{E}\right) \frac{(P_i - P_o) a^2 b^2}{(b^2 - a^2) r}$$

← plane stress

$$u = \frac{(1+\nu)(1-2\nu)}{E} \frac{(a^2 P_i - b^2 P_o) r}{b^2 - a^2} + \frac{1+\nu}{E} \frac{(P_i - P_o) a^2 b^2}{(b^2 - a^2) r}$$

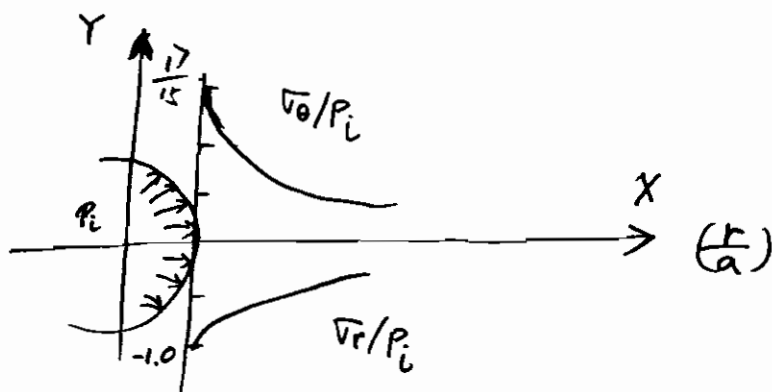
← plane strain

(1)  $P_o = 0$ ,

$$\sigma_r = \frac{a^2 P_i}{b^2 - a^2} \left(1 - \frac{b^2}{r^2}\right) < 0, \quad \text{Note that } \frac{b^2}{r^2} > 1, \quad a \leq r \leq b$$

$$\sigma_\theta = \frac{a^2 P_i}{b^2 - a^2} \left(1 + \frac{b^2}{r^2}\right) > 0, \quad \text{When } b \rightarrow \infty, \quad \sigma_\theta = P_i \text{ at } r = a,$$

$b/a = 4$

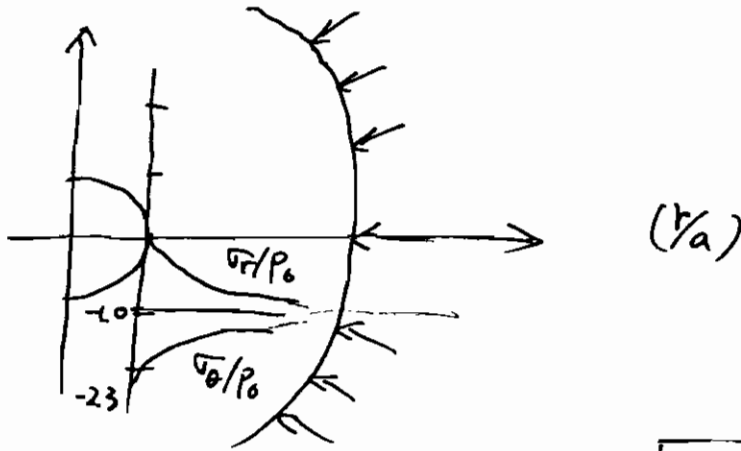


This is the limit you can do

(2)  $p_i = 0$

$\sigma_r = -\frac{p_0 b^2}{b^2 - a^2} \left(1 - \frac{a^2}{r^2}\right) < 0$ , Note that  $0 \leq \frac{a^2}{r^2} \leq 1$ ,  $a \leq r \leq b$

$\sigma_\theta = -\frac{p_0 b^2}{b^2 - a^2} \left(1 + \frac{a^2}{r^2}\right) < 0$



plane strain

$$\sigma_z = -\frac{2\nu (a^2 p_i - b^2 p_0)}{b^2 - a^2}$$

§ 16.2 Application of Failure Theories

⊛ Assume that this is plane strain state. Therefore

$\sigma_z = -\frac{\nu}{1-\nu} (\sigma_{rr} + \sigma_{\theta\theta}) = C.$

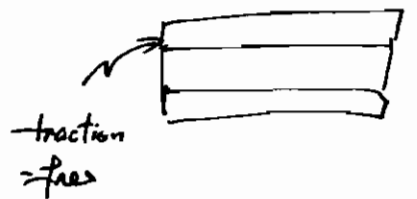


⊛ Assume that the ends of the cylinder are open and unconstrained,  $\sigma_z = 0$ .

$\int_a^b \sigma_z 2\pi r dr = \pi C (b^2 - a^2) = 0$

$C = 0$

$\Rightarrow \sigma_z = 0$



Tri-axial stress state

plane stress  $\rightarrow$  plane strain  $E \rightarrow \frac{E}{1-\nu^2}$ ,  $\nu \rightarrow \frac{\nu}{1-\nu}$

$$\left\{ \begin{array}{l} 1-\nu = 1 - \frac{\nu}{1-\nu} = \frac{1-2\nu}{1-\nu} \\ \frac{1}{E} = \frac{1-\nu^2}{E} \end{array} \right\} \frac{1-\nu}{E} = \frac{(1-\nu^2) \frac{1-2\nu}{1-\nu}}{E} = \frac{(1+\nu)(1-2\nu)}{E}$$

$$\left\{ \begin{array}{l} 1+\nu = 1 + \frac{\nu}{1-\nu} = \frac{1}{1-\nu} \\ \frac{1}{E} = \frac{1-\nu^2}{E} \end{array} \right\} \frac{1+\nu}{E} = \frac{1-\nu^2}{E} \frac{1}{1-\nu} = \frac{1+\nu}{E}$$

## § 16.2 Application of Failure theories

(\*) plane strain  $\epsilon_{zz} = 0$

$$\nu_{zz} = -\nu (\nu_r + \nu_\theta) = -2\nu \frac{a^2 p_i - b^2 p_o}{b^2 - a^2} = \text{const.}$$

(\*) plane stress  $\nu_{zz} = 0$

Consider plane stress

(1) Maximum shear stress theory

$$\{\sigma_\theta, \sigma_r, \sigma_\phi\}$$

At  $r=a$

$$\left\{ \begin{array}{l} \sigma_\theta, \sigma_r, \sigma_\phi \\ \downarrow \quad \downarrow \quad \downarrow \\ \sigma_1 > 0, \sigma_2 = 0, \sigma_3 < 0 \end{array} \right\}$$

$$p_\theta = 0$$

$$\tau_{max} = \frac{1}{2} (\sigma_\theta - \sigma_r) = \tau_{TP}$$

$$\frac{3}{4G} \tau_{oct}^2 = \bar{U}_d$$

(2) Maximum distortion energy theory

$$\bar{U}_d = \frac{1}{12G} [(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2]$$

$$= \frac{1}{6G} \tau_{TP}^2$$

$$\frac{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}{3} \cong \tau_{oct}^2 = \left(\frac{\sqrt{2}}{3}\right)^2 \tau_{TP}^2$$

$$\tau_{TP} = \frac{1}{\sqrt{2}} \sqrt{(\sigma_1 - \sigma_2)^2 + (\sigma_2 - \sigma_3)^2 + (\sigma_3 - \sigma_1)^2}$$

$$= \frac{1}{\sqrt{2}} \sqrt{(\sigma_\theta)^2 + \sigma_r^2 + (\sigma_\theta - \sigma_r)^2}$$

$\tau_{oct}$

Octahedral stress

$$\tau_{TP} = \sqrt{\sigma_\theta^2 + \sigma_r^2 - \sigma_\theta \sigma_r}$$

Example 8.2

$$\tau_{TP} = \sigma_{TP}/2 = 170 \text{ MPa}$$

$$a = 0.1 \text{ m} \quad b = 0.15 \text{ m}$$

$$\frac{b}{a} = \frac{3}{2} = 1.5$$

$$P_i = 4P_0$$

Find the allowable  $P_i$ ?

Solution :

$$\sigma_{\theta} = \frac{P_i (a^2 + b^2) - 2P_o b^2}{b^2 - a^2} = 1.7 P_i, \quad \sigma_r = -P_i$$

(1) Maximum shear stress criterion

$$\frac{\sigma_{\theta} - \sigma_r}{2} = \frac{1.7 P_i - (-P_i)}{2} = 1.35 P_i = \tau_{yp} = 170 \text{ MPa}$$

$$\Rightarrow P_i = \frac{170}{1.35} = 125.9 \text{ MPa}$$

Compare with

$$\tau_{yp} = 340 \text{ MPa}$$

Conventional wisdom

(2) Maximum distortion energy criterion

$$\tau_{yp} = \sqrt{\sigma_{\theta}^2 + \sigma_r^2 - \sigma_{\theta} \sigma_r}$$

$$= \sqrt{(1.7 P_i)^2 + P_i^2 + 1.7 P_i^2} = P_i \sqrt{1.7^2 + 1 + 1.7}$$

$$= 2.364 P_i = 340 \text{ MPa}$$

$$P_i = 143.8 \text{ MPa}$$

If  $b \rightarrow \infty$ ,  $\sigma_{\theta} = P_i$ ,  $\sigma_r = -P_i$ ,  $\sigma_z = 0$

The best you can do

$$\frac{\sigma_{\theta} - \sigma_r}{2} = \frac{P_i - (-P_i)}{2} = P_i = 170 \text{ MPa}$$

$$\tau_{yp} = 340 \text{ MPa}$$